

# Module Computer Vision

Module Name: Computer Vision

Module Number	<b>X4M 2330</b>	Level	Master	Short CV Name
Responsible Lecturers	Prof. Dr. Erhardt Barth			
Department, Facility	UZL, Institute of Neuro- and Bioinformatics			
Course of Studies	Biomedical Engineering, Master			
Compulsory/elective	Elective	ECTS Credit Points	4	
Semester of Studies	2	Semester Hours per Week	3	
Length (semesters)	1	Workload (hours)	120	
Frequency	SuSe	Presence Hours	50	
Teaching Language	English	Self-Study Hours	70	
Consideration of Gender and Diversity Issues	<input checked="" type="checkbox"/> Use of gender-neutral language (THL standard) <input type="checkbox"/> Target group specific adjustment of didactic methods <input type="checkbox"/> Making subject diversity visible (female researchers, cultures etc.)			
Applicability	Biomedical Engineering			
Remarks	None			

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### Course 1: Computer Vision Lecture and Exercise

Course Number		Short Name	CV
Course Type	Lecture and exercise	Form of Learning	Presence
Mandatory Attendance	X	ECTS Credit Points	4
Participation Limit	None	Semester Hours per Week	3
Group Size (practical training, exercises, ...)	None	Workload (hours)	120
Teaching Language	English	Presence Hours	50
Study Achievements („Studienleistung“, SL)	None	Self-Study Hours	70
SL Length (minutes)	n. a.	SL Grading System	n. a.
Exam Type	Oral Exam	Exam Language	English
Exam Length (minutes)	20	Exam Grading System	One-third Grades
Learning Outcomes	<p>Students can understand the basics of computer vision.</p> <p>They can explain and perform camera choice and calibration.</p> <p>They can explain and apply the basic methods for feature extraction, motion estimation, and object recognition.</p> <p>They can indicate appropriate methods for different kinds of computer-vision applications.</p>		
Participation Prerequisites	Basic knowledge in signal processing		
Contents	<ul style="list-style-type: none"> <li>• Introduction to human and computer vision</li> <li>• Sensors, cameras, optics and projections</li> <li>• Image features: edges, intrinsic dimension, Hough transform, Fourier descriptors, snakes</li> <li>• Range imaging and 3-D cameras</li> <li>• Motion and optical flow</li> <li>• Object recognition</li> <li>• Example applications</li> </ul>		
Literature	<p>Richard Szeliski: Computer Vision: Algorithms and Applications. Springer, Boston, 2011</p> <p>I David Forsyth and Jean Ponce: Computer Vision: A Modern Approach. Prentice Hall, 2003</p> <p>Hand-out from lecturer</p>		
Remarks	None		